

EECS 120  
Midterm 1  
Wed. Feb. 26, 2014  
1610 - 1730 pm

Name: \_\_\_\_\_

SID: \_\_\_\_\_

- Closed book. One 8.5x11 inch page one side formula sheet. No calculators.
- There are 4 problems worth 100 points total. There may be more time efficient methods to solve problems.

Problem	Points	Score
1	21	
2	27	
3	25	
4	27	
TOTAL	100	

In the real world, unethical actions by engineers can cost money, careers, and lives. The penalty for unethical actions on this exam will be a grade of zero and a letter will be written for your file and to the Office of Student Conduct.

Tables for reference:

$\tan^{-1} \frac{1}{2} = 26.6^\circ$	$\tan^{-1} 1 = 45^\circ$
$\tan^{-1} \frac{1}{3} = 18.4^\circ$	$\tan^{-1} \frac{1}{4} = 14^\circ$
$\tan^{-1} \sqrt{3} = 60^\circ$	$\tan^{-1} \frac{1}{\sqrt{3}} = 30^\circ$
$\sin 30^\circ = \frac{1}{2}$	$\cos 60^\circ = \frac{\sqrt{3}}{2}$
$\cos 45^\circ = \frac{\sqrt{2}}{2}$	$\sin 45^\circ = \frac{\sqrt{2}}{2}$

$20 \log_{10} 1 = 0dB$	$20 \log_{10} 2 = 6dB$
$20 \log_{10} \sqrt{2} = 3dB$	$20 \log_{10} \frac{1}{2} = -6dB$
$20 \log_{10} 5 = 20dB - 6dB = 14dB$	$20 \log_{10} \sqrt{10} = 10 dB$
$1/e \approx 0.37$	$1/e^2 \approx 0.14$
$1/e^3 \approx 0.05$	$\sqrt{10} \approx 3.16$

**Problem 1 LTI Properties (21 pts)**

[15 pts] Classify the following systems, with input  $x(t)$  and output  $y(t)$ . In each column, write “yes”, “no”, or “?” if the property is not decidable with the given information. (+1 for correct, 0 for blank, -0.5 for incorrect).

System	Causal	Linear	Time-invariant
a. $y(t) = x(t) \cos(2\pi t)$			
b. $y(t) = x(t) * u(t - 2)$			
c. $y(t) = 3x(t + 1) + 1$			
d. $y(t) = \int_{-\infty}^{\infty} x(\tau)x(t - \tau)d\tau$			
e. $y(t) = x(t) - \frac{1}{2} \frac{dy(t)}{dt}$			

[6 pts] Two of the systems above (a,b,c,d,e) are not BIBO stable. Note below which systems are not BIBO stable, and then find a bounded input  $x(t)$  which gives rise to an unbounded output  $y(t)$  for each of these systems.

System 1:

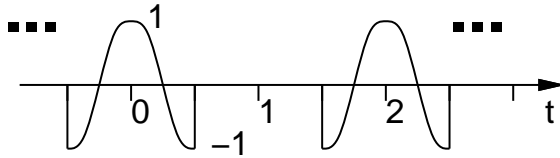
Bounded input  $x(t) = \underline{\hspace{2cm}}$

System 2:

Bounded input  $x(t) = \underline{\hspace{2cm}}$

**Problem 2 Fourier Series (27 pts)**

You are given a periodic function  $x(t)$  as shown, where the shape is one period of a cosine:



$x(t)$  can be represented by a Fourier Series:

$$x(t) = \sum_{k=-\infty}^{\infty} x_k e^{jk\omega_0 t}$$

[2 pts] a. What is the fundamental frequency  $\omega_0 =$  \_\_\_\_\_

[8 pts] b. Find  $x_k =$  \_\_\_\_\_

Problem 2, continued.

A periodic signal  $c(t)$  with period  $T_o = 2$  seconds has complex Fourier series coefficients  $c_k$  where:

$$c_k = \frac{1}{2} \left[ \frac{\sin \frac{(1-k)\pi}{2}}{\pi(1-k)} + \frac{\sin \frac{(1+k)\pi}{2}}{\pi(1+k)} \right]$$

[2 pts] c. What is the time average DC power in  $c(t)$ ? \_\_\_\_\_

[3 pts] d. What is the time average power in the fundamental frequency component  $\omega_o$ ? \_\_\_\_\_

The signal  $c(t)$  is passed through a filter with frequency response  $H(j\omega)$ , with:

$$H(j\omega) = 1 - e^{-j\omega},$$

and the output of the filter is  $d(t)$ , where  $d(t) = \sum_{k=-\infty}^{\infty} d_k e^{jk\pi t}$ .

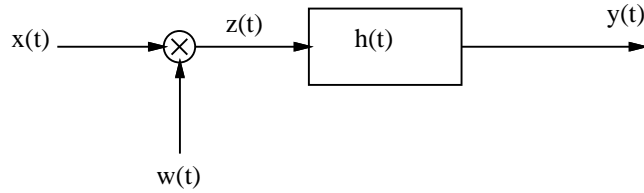
[8 pts] e. Find  $d_k$  (leave as an expression) = \_\_\_\_\_

[4 pts] f. Complete the table for specific frequency components, simplifying if possible:

k	d(k)
0	
1	
2	
3	

**Problem 3. Fourier Transform (25 pts)**

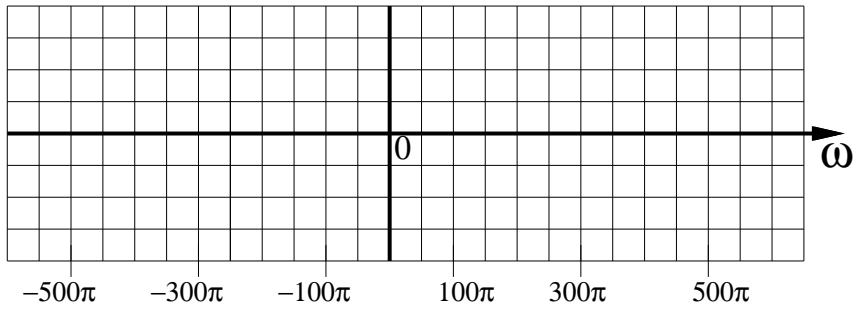
For each part below, consider the following system:



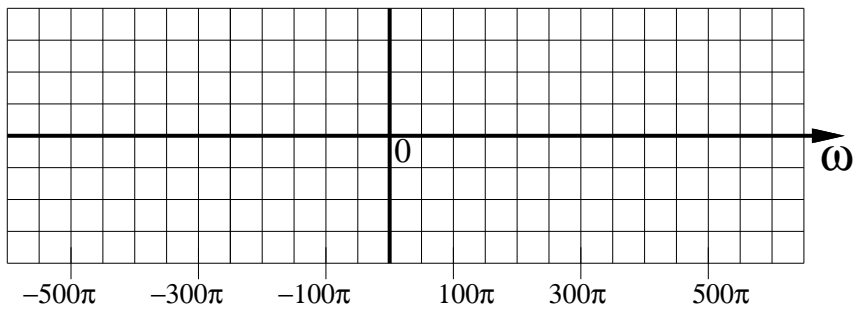
Where  $x(t) = \cos(400\pi t) + \frac{\sin 100\pi t}{\pi t}$ ,  $w(t) = \frac{\sin 50\pi t}{\pi t}$ ,  $h(t) = \frac{\sin 100\pi t}{\pi t}$

Sketch  $ReX(j\omega)$ ,  $ReZ(j\omega)$ ,  $ReY(j\omega)$  labelling height/area, center frequencies, and key zero crossings for  $-500\pi \leq \omega \leq 500\pi$ :

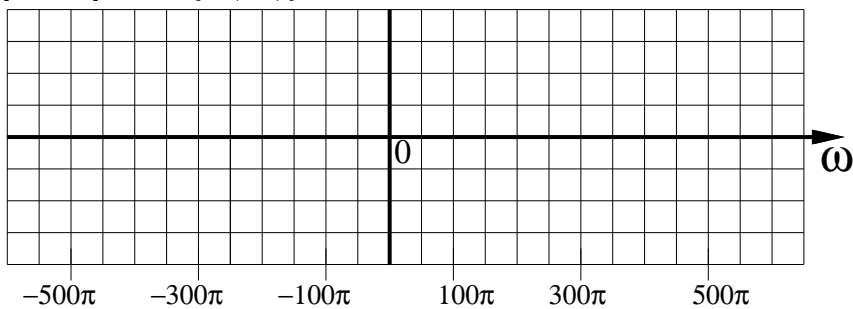
[5 pts] a.  $Re\{X(j\omega)\}$



[10 pts] b.  $Re\{Z(j\omega)\}$



[10 pts] c.  $Re\{Y(j\omega)\}$



**Problem 4. DTFT (27 points)**

A causal LTI system with input  $x[n]$  and output  $y[n]$  is described by the difference equation:

$$y[n] - y[n - 1] = x[n]$$

[4 pts] a. Find  $H(e^{j\omega})$  the transfer function for the system = \_\_\_\_\_

[2 pts] b. Find the impulse response  $h[n]$ , that is, the time response of the system to input  $x[n] = \delta[n]$ .

$$h[n] = \underline{\hspace{2cm}}$$

[10 pts] c. If  $x[n] = 2 \cos(\frac{1}{2}\pi n)$  find  $y[n]$ .  $y[n] = \underline{\hspace{2cm}}$

[4 pts] d. Show that  $y[n]$  is real in part c (above).

Problem 4, continued.

[4 pts] e. An LTI system has transfer function  $K(e^{j\omega}) = \frac{L(e^{j\omega})}{M(e^{j\omega})} = 2 \cos(\omega) + 2j \sin(2\omega)$ .

Write the difference equation for this system with input  $m[n]$  and output  $l[n]$ :

$$l[n] = \underline{\hspace{10em}}$$

[3 pts] f. A signal  $x[n]$  has DTFT  $X(e^{j\omega})$ .

Another signal  $y[n] = x[-2n + 4]$ . Find the DTFT of  $y[n]$  in terms of  $X(e^{j\omega})$ .

$$Y(e^{j\omega}) = \underline{\hspace{10em}}$$