University of California at Berkeley Department of Electrical Engineering and Computer Sciences Professor J.M. Kahn, EECS 120, Fall, 1997 Final Examination, Wednesday, December 17, 1997, 5-8 pm

NAME:

- 1. The exam is closed-book. You are permitted to use three, two-sided pages of notes. No calculators are permitted.
- 2. Do all work in the space provided. If you need more room, use the back of previous page.
- 3. Indicate your answer clearly by circling it or drawing a box around it.

Problem	1	2	3	4	5	6	TOTAL
Points	75	30	30	25	30	10	200
Score							

Problem 1 (75 pts.) A LTI discrete-time system with input x[n] and output y[n] has an impulse response:

$$h[n] = 12\left[\left(-\frac{1}{3}\right)^n - \left(-\frac{1}{2}\right)^n\right]u[n].$$

A sketch of h[n] is shown here.



(a) (5 pts.) Give a closed-form expression for the system transfer function H(z).

(b) (5 pts.) Find the poles and zeros of H(z), and sketch them on the z-plane below.



(c) (5 pts.) Find the output y[n] when input is $x[n] = 3^n$, $\forall n$.

(d) (5 pts.) Clearly the frequency response $H(e^{j\Omega})$ exists. Sketch the magnitude response $|H(e^{j\Omega})|$, labeling the vertical and horizontal axes of your plot.



(e) (10 pts.) Evaluate $\int_{0}^{2\pi} H(e^{j\Omega})e^{-j\Omega}d\Omega$ without explicitly using the expression for $H(e^{j\Omega})$.



(g) (15 pts.) Find an expression for the step response $y_s[n]$.

The step response exhibits overshoot, which is troublesome in many applications. It is proposed to compensate for the overshoot by cascading with another system g[n], as shown below.

$$x[n] \rightarrow h[n] \rightarrow y[n]$$

 $y[n] \rightarrow y[n]$

The system g[n] is described by the difference equation:

$$w[n] = ay[n] + by[n-1] + cy[n-2].$$

(h) (15 pts.) Find values of the constants *a*, *b*, and *c* such that the cascaded system (with input x[n] and output w[n]) has a step response that is simply a delayed unit step, $w_s[n] = u[n-1]$.

(i) (5 pts.) Sketch a realization of the system g[n].

Problem 2 (30 pts.) Consider the discrete-time system enclosed in the dashed box, which has input x[n] and output y[n].



Suppose that the input x[n] has the discrete-time Fourier transform $X(e^{j\Omega})$ shown below.



(a) (15 pts.) Sketch $V(e^{j\Omega})$, $W(e^{j\Omega})$, and $Y(e^{j\Omega})$, which are the discrete-time Fourier transforms of v[n], w[n], and y[n], respectively.



Evidently, the system enclosed in the dashed box is equivalent to a LTI system $g[n] \leftrightarrow G(e^{j\Omega})$. (b) (5 pts.) Sketch the frequency response $G(e^{j\Omega})$.



(c) (10 pts.) Give an expression for the impulse response g[n].

Problem 3 (30 pts.) Consider the LTI continuous-time system *H* enclosed in the outer dashed box, which has input x(t) and output y(t). *K* is a real constant, $-\infty < K < \infty$.



(a) (10 pts.) Find the transfer function H(s) = Y(s)/X(s). *Hint*: first consider *G*, the system enclosed in the inner dotted box, which has input y(t) and output w(t). It has transfer function G(s) = W(s)/Y(s).

(b) (5 pts.) H(s) has one zero at s = z, and one pole at s = p. Find z and p in terms of K. Sketch p as a as a function of K, labeling the vertical and horizontal axes of your plot. For what values of K is the system H stable?



(c) (15 pts.) Assume that K = 1/3. Make Bode plots of the magnitude and phase of the frequency response $H(j\omega)$, labeling the horizontal and vertical axes carefully.



Problem 4 (25 pts.) As studied in class, Parseval's identity for the continuous-time Fourier transform states that for $x(t) \leftrightarrow X(\omega)$:

$$\int_{-\infty}^{\infty} x^*(t)x(t)dt = \frac{1}{2\pi}\int_{-\infty}^{\infty} X^*(\omega)X(\omega)d\omega.$$

(a) (15 pts.) Consider $x_1(t) \leftrightarrow X_1(\omega)$ and $x_2(t) \leftrightarrow X_2(\omega)$. Prove a generalization of the identity:

$$\int_{-\infty}^{\infty} x_1^*(t) x_2(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} X_1^*(\omega) X_2(\omega) d\omega .$$

(b) (10 pts.) Let x(t) be a real signal, and let $\hat{x}(t)$ be its Hilbert transform. Use the result of part (a) to evaluate the integral:

$$\int_{-\infty}^{\infty} x^*(t) \hat{x}(t) dt.$$

Problem 5 (30 pts.) Consider the following system.



The signal x(t) is bandlimited to $|\omega| \le \omega_m$, It is multiplied by p(t), the periodic signal shown. The product, y(t), is passed through the ideal lowpass filter $H(\omega)$, which has cutoff frequency W and gain G.

(a) (10 pts.) Since p(t) is periodic with period $T_0 = 4$, it can be represented as a Fourier series:

$$p(t) = \sum_{n = \infty}^{\infty} P_n e^{\frac{jn\pi t}{2}}$$

Without explicitly calculating the P_n , find an expression for $Y(\omega)$, the Fourier transform of y(t), in terms of $X(\omega)$ and the P_n .

(b) (20 pts.) State the conditions on ω_m , W and G such that z(t) = x(t). Be as specific as possible, replacing variables by specific numbers when possible.

Problem 6 (10 pts.) A discrete-time LTI system has transfer function:

$$H(z) = \frac{1}{1 - z^{-17} - z^{-19}}.$$

The input is $x[n] = a^n u[n]$. Assuming y[n] = 0, n < 0, find y[15].