

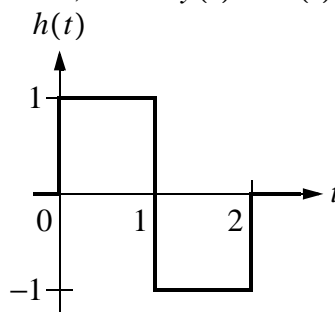
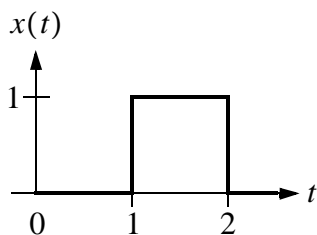
**University of California at Berkeley**  
**Department of Electrical Engineering and Computer Sciences**  
**EECS 120, Professor J.M. Kahn**  
**Midterm 1**  
**Wednesday, October 9, 2002, 2:15-3:15 pm**

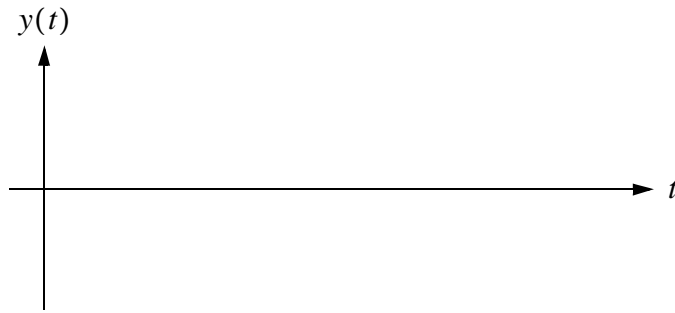
Name: \_\_\_\_\_

**Note: indicate your answer clearly by circling it or drawing a box around it. When asked to make sketches of functions, label the horizontal and vertical axes of the plots.**

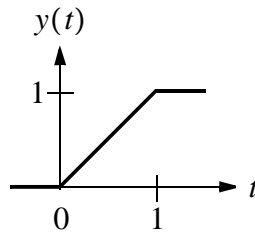
Problem	Points	Score
1	15	
2	30	
3	40	
4	15	
TOTAL:	100	

**Problem 1** (15 pts.) Given the signals  $x(t)$  and  $h(t)$  shown, sketch  $y(t) = x(t)*h(t)$ .





**Problem 2** (30 pts.) Consider an LTI CT system. When the input is  $x(t) = r(t) = t \cdot u(t)$ , the output  $y(t)$  is as shown.

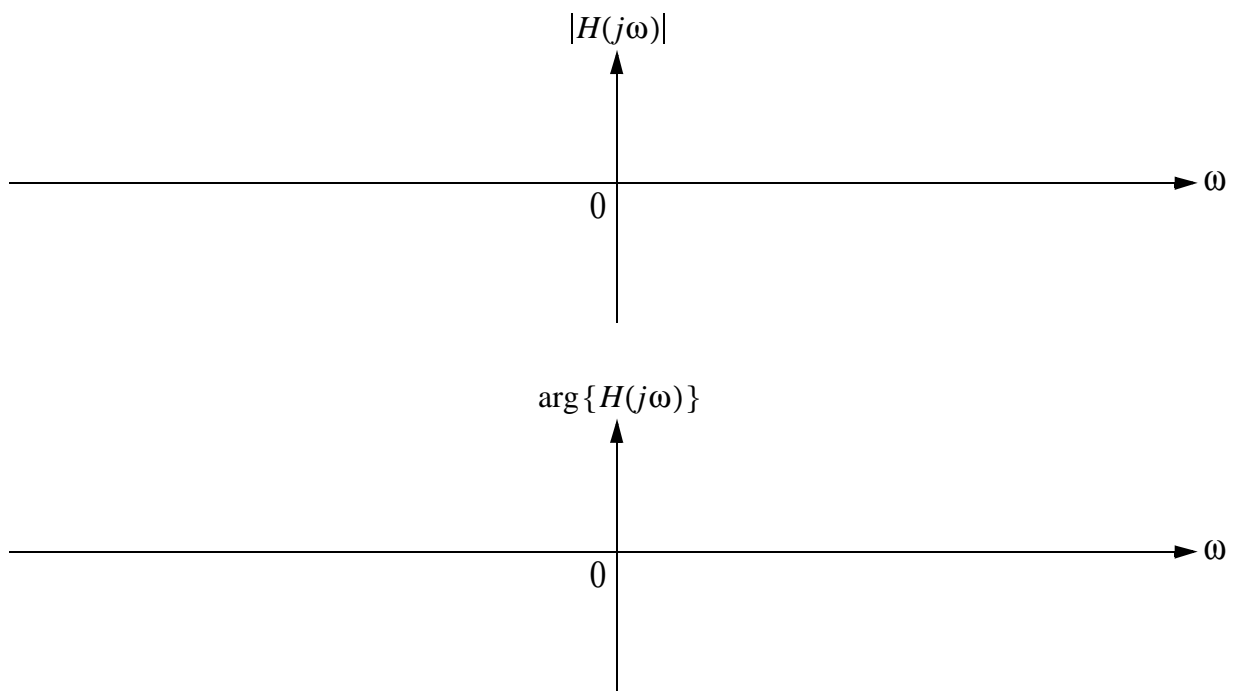


(a) (10 pts.) Find an expression for the system step response  $s(t)$  and sketch  $s(t)$ .

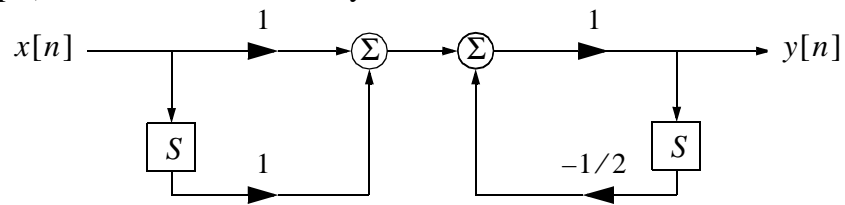


(b) (10 pts.) Find an expression for the system frequency response  $H(j\omega)$ .

- (c) (10 pts.) Sketch the magnitude and phase of  $H(j\omega)$ . If you find that  $H(j\omega)$  is periodic, you may plot only one period.



**Problem 3** (40 pts). Consider the LTI DT system shown.



(a) (5 pts.) State the difference equation governing the system.

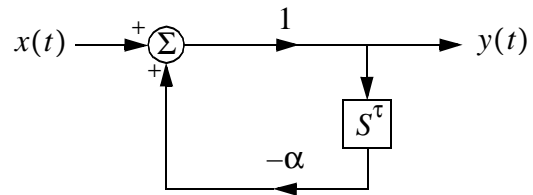
(b) (10 pts.) Find the system frequency response  $H(e^{j\Omega})$ .

(c) (5 pts.) The input is  $x[n] = \cos\Omega_0 n$ ,  $\forall n$ . Find  $\Omega_0$ ,  $0 \leq \Omega_0 < 2\pi$ , such that  $y[n] = 0$ ,  $\forall n$ .

(d) (20 pts.) Find the system step response  $s[n]$ .



**Problem 4** (15 pts.) Consider the LTI CT system shown.



(a) (5 pts.) Find an expression for the impulse response  $h(t)$ .

(b) (10 pts.) For what values of  $\alpha$  is the system stable?