

**EE 120 Fall 1994
Midterm #2
Professor Fearing**

Problem #1 (10 points)

A modulation scheme is described by:

$$x(t) = \cos(\omega_c t + \phi_{\text{DELTA}} m(t))$$

where

$$\omega_c = 2 \pi \cdot 10^3$$

$$\phi_{\text{DELTA}} = \phi$$

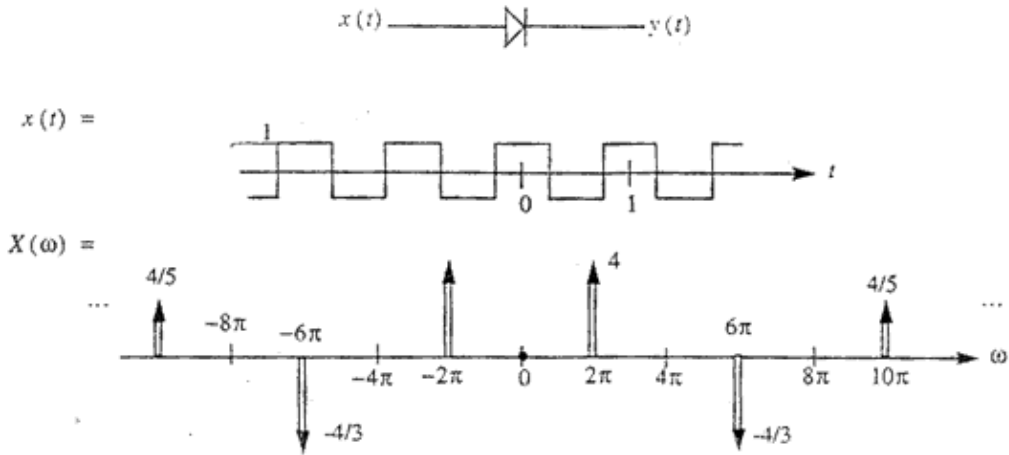
$$m(t) = PI(t) = u(t + 1/2) - u(t - 1/2)$$

[2 pts.] a) Sketch $x(t)$.

[8 pts.] b) Sketch $\text{Re}\{X(\omega)\}$, noting maximum amplitudes, center frequencies, and frequency of first zero crossing.

Problem #2 (10 points)

A square wave $x(t)$ is passed through an ideal diode. Sketch the spectrum at the output of the ideal diode $Y(\omega)$, labelling important frequencies and amplitudes. Recall for an ideal diode that $v_{\text{out}} = \{ 0, v_{\text{in}} < 0 \text{ and } v_{\text{in}}, v_{\text{in}} \geq 0 \}$.

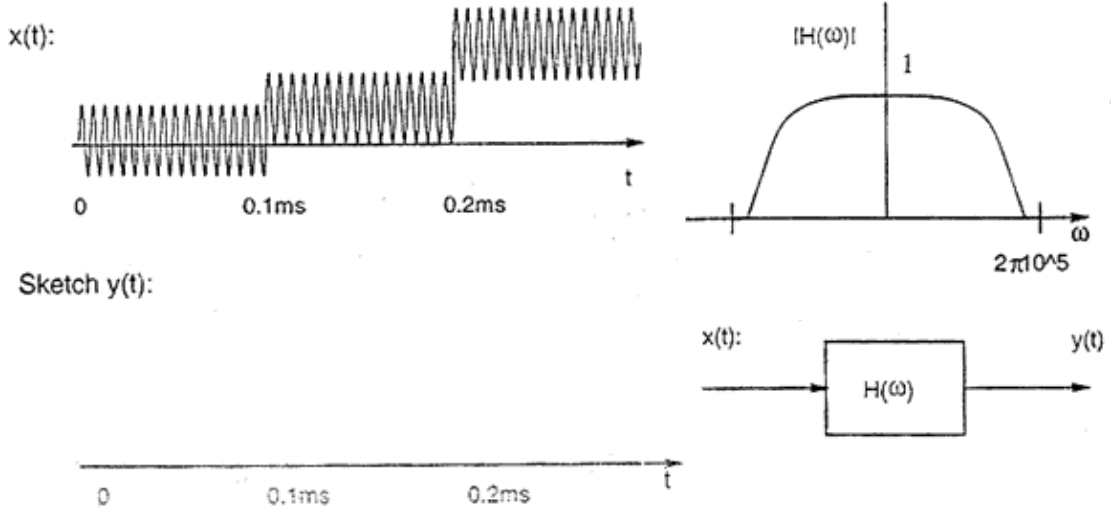


Sketch $Y(\omega)$.



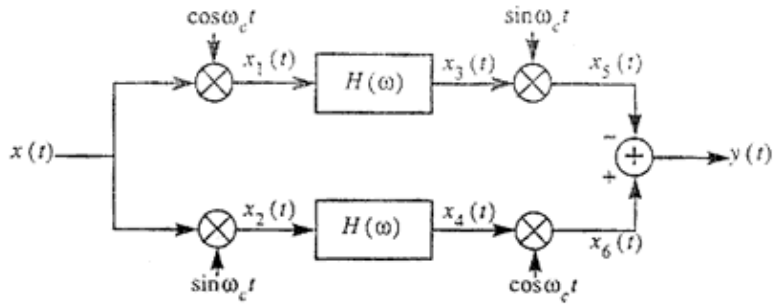
Problem #3 (5 points)

The signal $x(t)$ is passed through a lowpass filter with frequency response $H(\omega)$. The signal $x(t)$ contains a sinusoidal component at 100 KHz. Sketch approximately $y(t)$, the output in time of the lowpass filter for the input $x(t)$.

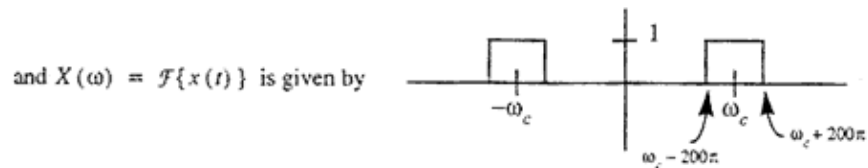


Problem #4 (25 points)

You are given the following modulation scheme:



where $H(\omega) = \begin{cases} j, & \omega > 0 \\ -j, & \omega < 0 \end{cases}$

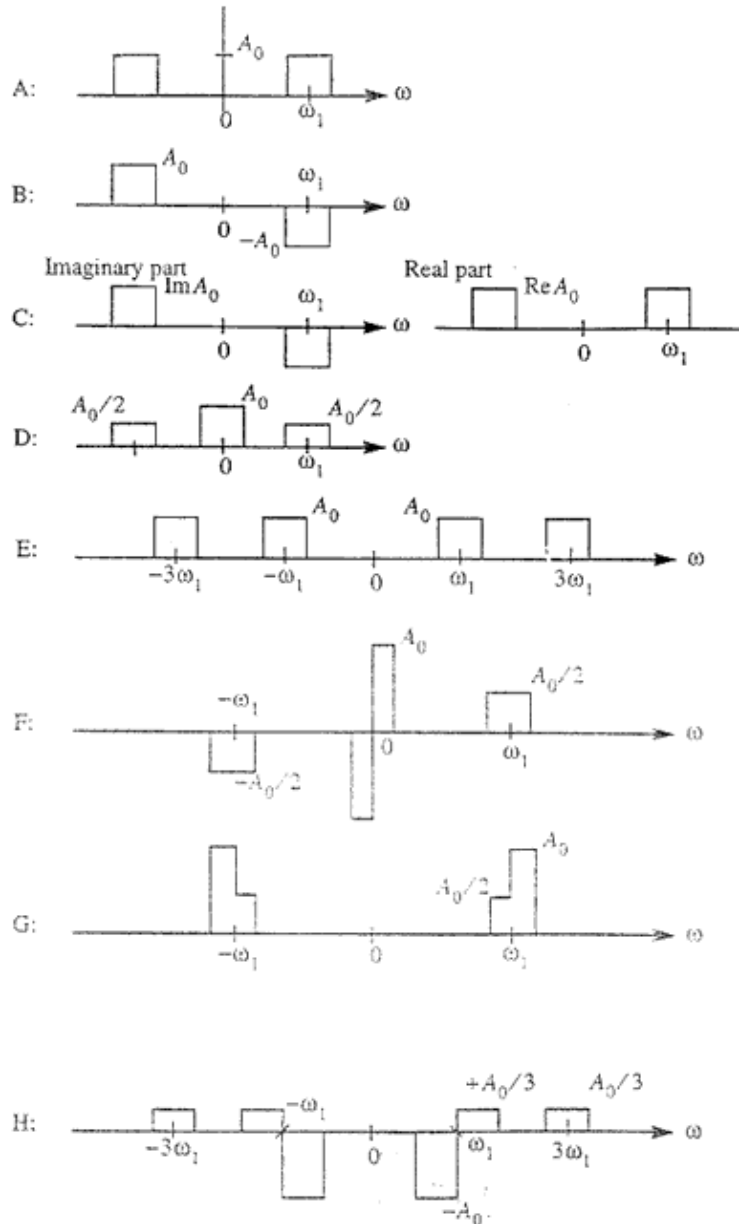


For each signal $x_1(t), x_2(t), \dots, x_6(t), y(t)$ select one of the following sketches, specifying amplitude A_0 and frequency ω_1 . (Hint: Amplitude A_0 may be complex.)

	letter of sketch	A_0	ω_1
$X_1(\omega)$			

$X_2(\omega)$			
$X_3(\omega)$			
$X_4(\omega)$			
$X_5(\omega)$			
$X_6(\omega)$			
$Y(\omega)$			

The following sketches represent spectra of the signals $x_1(t) \dots x_6(t)$, and $y(t)$. The horizontal and vertical scale in each sketch are arbitrary, and should be considered independently.



Problem #5 (7 points)

A causal system is described by the following differential equation (with input $x(t)$ and output $y(t)$) :

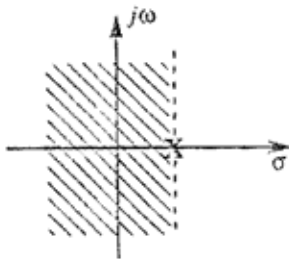
$$dy/dt = d^2x/dt^2 + 3 dx/dt + 2 x$$

Assuming zero initial conditions,

- a) Is this system BIBO stable?
- b) Find $Y(s)$ and $y(t)$ for $x(t) = 0$ and $y(0^-) = -5$.

Problem #6 (3 points)

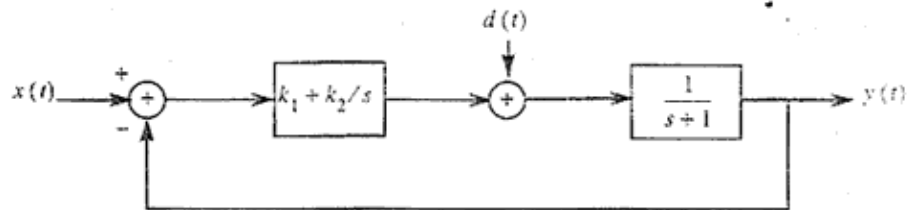
A system has Laplace Transform $X(s)$ with ROC $\sigma < 2$.



The system is (circle one) :

- a) stable but not causal
- b) causal but not stable
- c) stable and causal
- d) neither stable nor causal

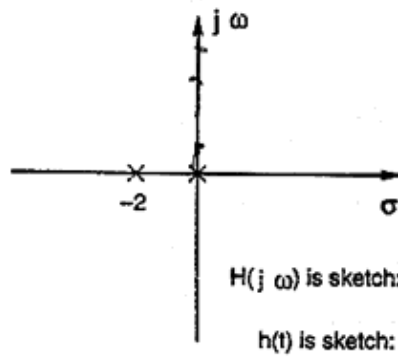
Problem #7 (15 points)



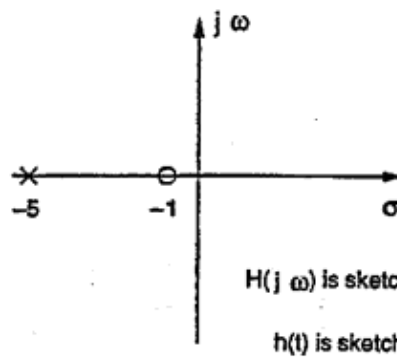
- a) With $d(t) = 0$, compute $Y(s)/X(s)$.
- b) For which values of k_1 and k_2 is the system stable?
- c) Let $d(t) = u(t)$ and $x(t) = 0$, with $k_1 = 1$ and $k_2 = 1$. What is the limit of $y(t)$ as t approaches infinity? (answer should be a **number**)
- d) Let $d(t) = 0$ and $x(t) = u(t)$, with $k_1 = 1$ and $k_2 = 1$. What is the limit of $y(t)$ as t approaches infinity? (answer should be a **number**)

Problem #8 (25 points)

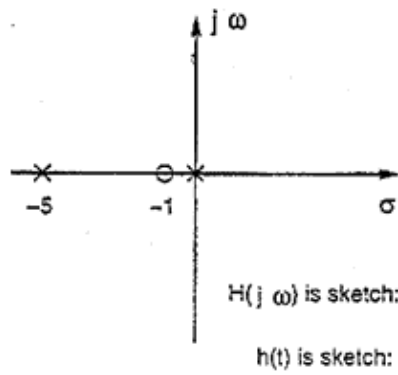
For each pole-zero diagram below, fill in the box with the letter of the corresponding frequency response and impulse response that follow. All diagrams represent causal systems.



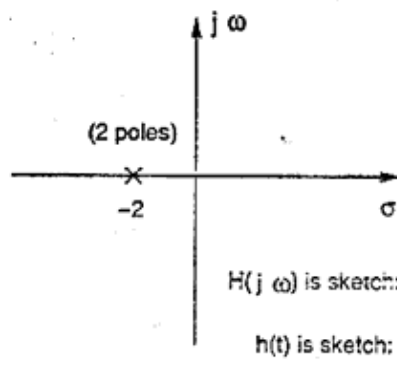
$H(j\omega)$ is sketch:
 $h(t)$ is sketch:



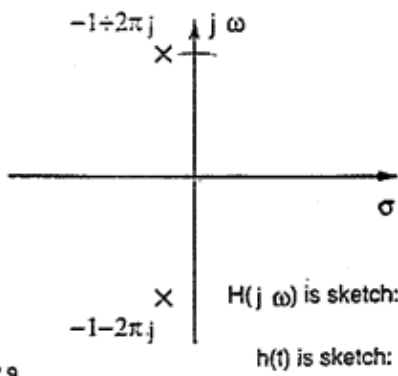
$H(j\omega)$ is sketch:
 $h(t)$ is sketch:



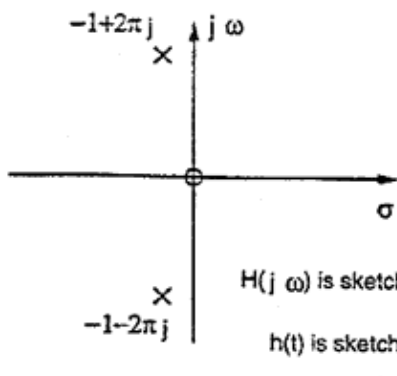
$H(j\omega)$ is sketch:
 $h(t)$ is sketch:



$H(j\omega)$ is sketch:
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$H(j\omega)$ is sketch:
 $h(t)$ is sketch:

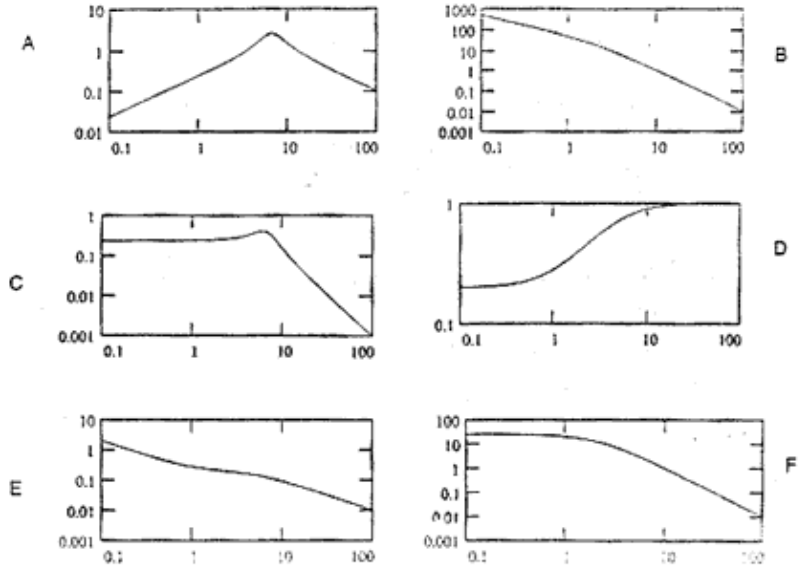


$H(j\omega)$ is sketch:
 $h(t)$ is sketch:

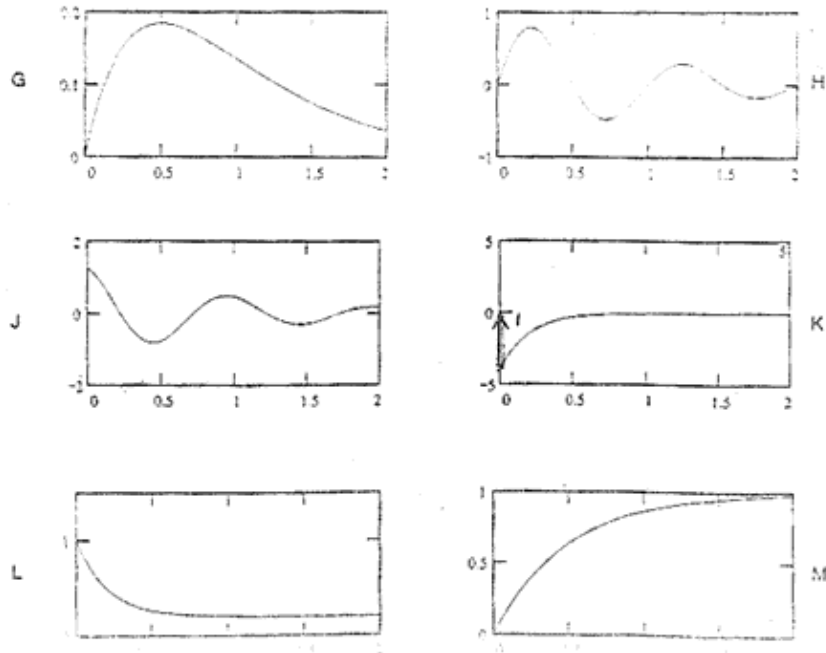
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Sketches to be used as answers for problem #8.

Magnitude of the frequency response $|H(j\omega)|$:



Impulse Responses



Solutions (page 1)
Solutions (page 2)

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